

1.2 APPLIED MATHEMATICS I
[Common to All Engineering Courses]

L T P
3 2/2 -

Rationale:

The study of mathematics is an important requirement for the understanding and development of any branch of engineering. The purpose of teaching mathematics to diploma engineering students is to impart them basic knowledge of mathematics which is needed for full understanding and study of engineering subjects.

S.N.	Units	Coverage Time		
		L	T	P
1.	Algebra-I	18	6	-
2.	Trigonometry	7	2	-
3.	Coordinate Geometry	15	5	-
4.	Differential Calculus-I	15	5	-
5.	Integral Calculus-I	20	7	-
		75	25	-

DETAILED CONTENTS:

1. ALGEBRA-I :

1.1 Series : AP and GP; Sum, nth term, Mean

1.2 Binomial theorem for positive, negative and fractional index (without proof). Application of Binomial theorem.

1.3 Determinants : Elementary properties of determinant of order 2 and 3, Multiplication system of algebraic equation, Consistency of equation, Cramer's rule

1.4 Vector algebra : Dot and Cross product, Scaler and vector triple product.

2. TRIGONOMETRY :

2.1 Relation between sides and angles of a triangle : Statement of various formulae showing relation ship between sides and angle of a triangle.

2.2 Complex number.

Complex numbers, Representation, Modulus and amplitud Demoivre theorem, its application in solving algebraic equations, Mod. function and its properties..

2.3 Inverse circular functions and Hyperbolic Functions: Simple

case only

3. CO-ORDINATE GEOMETRY :

3.1 Standard form of curves and their simple properties -

Parabola $x^2=4ay$, $y^2=4ax$,

Ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

Hyperbola $\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$

Tangent and normals

3.2 Straight lines, planes and spheres in space -

Distance between two points in space, direction ratios, Finding equation of a straight line, and shortest distance between two lines

Under different conditions equation of a plane $lx+my+nz=c$, relation between lines and planes, sphere $x^2 + y^2 + z^2 + 2gx + 2fy + 2wz=d$

4. DIFFERENTIAL CALCULUS - I :

4.1 Functions, limits, continuity, - functions and their graphs, range and domain, elementary methods of finding limits (right and left), elementary test for continuity and differentiability.

4.2 Methods of finding derivative, - Function of a function, Logarithmic differentiation, Differentiation of implicit functions, Higher order derivatives, Leibnitz theorem.

4.3 Special functions (Exponential, Logarithmic, Hyperbolic, Inverse circular and function), Definition, Graphs, range and Domain and Derivations of each of these functions.

4.4 Application - Finding Tangents, Normal, Points of Maxima/Minima, Increasing/Decreasing functions, sketching of some simple curves (without assumptions, question, not to be asked in the examination), Rate, Measure, velocity, Acceleration, Errors and approximation.

5. INTEGRAL CALCULUS - I :

5.1 Methods of Indefinite Integration :- Integration by substitution, Partial fraction and by parts, Integration of special function of 4.3.

5.2 Meaning and properties of definite integrals, Evaluation of

definite integrals.

- 5.3 Application : Finding areas bounded by simple curves, Length of simple curves, Volume of solids of revolution, centre of mean of plane areas.
- 5.4 Simpsons and Trapezoidal Rule : their application in simple cases, Concept of error for simple function.

2.1 APPLIED MATHEMATICS II

[Common to All Engineering Courses]

L	T	P
3	1	-

Rationale :

The study of mathematics is an important requirement for the understanding and development of concepts of Engg. The purpose of teaching mathematics to the Diploma Engg. students is to give them basic foundation and understanding of mathematics so that they can use the same for the understanding of engineering subjects and their advancements.

Sl.No.	Units	Coverage Time		
		L	T	P
1.	Matrices	15	5	-
2.	Ordinary Differential Equations	15	5	-
3.	Differential Calculus-II	15	5	-
4.	Integral Calculus-II	15	5	-
5.	Probability & Statistics	15	5	-
		75	25	-

DETAILED CONTENTS

1. MATRICES :

1.1 Algebra of Matrices, Inverse :

Addition, Multiplication of matrices, Null matrix and a unit matrix, Square matrix, Determinant of a matrix, Cofactors, Definition and Computation of inverse of a matrix.

1.2 Elementary Row/Column Transformation :

Meaning and use in computing inverse and rank of a matrix.

1.3 Linear Dependence, Rank of a Matrix :

Linear dependence/independence of vectors, Definition and computation of a rank of matrix. Computing rank through determinants, Elementary row transformation and through the concept of a set of independent vectors, Consistency of equations.

1.4 Types of Matrices :

Symmetric, Skew symmetric, Hermitian, Skew hermitian, Orthogonal, Unitary, diagonal and Triangular.

1.5 Eigen Pairs, Cayley-Hamilton Theorem :

Definition and evaluation of eigen values and eigen vectors of a matrix of order two and three, Cayley-Hamilton theorem (without Proof) and its verification, Use in finding inverse and powers of a matrix.

2. ORDINARY DIFFERENTIAL EQUATION :

2.1 Formation, Order, Degree, Types, Solution :

Formation of differential equations through physical, geometrical, mechanical and electrical considerations, Order, Degree and Meaning of solution of a differential equation, Linear, Nonlinear equation.

2.2 First Order Equations :

Variable separable, equations reducible to separable forms, Homogeneous equations, equations reducible to homogeneous forms, Linear and Bernoulli form exact equation and their solutions.

2.3 Higher Order Linear Equation :

Property of solution, Linear equation with constant coefficients, Cauchy type equation. Homogeneous and Non-homogeneous equations, equations reducible to linear form with constant coefficients.

2.4 Simple Applications :

LCR circuit, Motion under gravity, Newton's law of cooling, radioactive decay, Population growth, Force vibration of a mass point attached to spring with and without damping effect. Equivalence of electrical and mechanical system

3. DIFFERENTIAL CALCULUS-II :

3.1 Function of two variables, identification of surfaces in space, conicoids

3.2 Partial Differentiation :

Directional derivative, Gradient, Use of gradient f , Partial derivatives, Chain rule, Higher order derivatives, Euler's theorem for homogeneous functions, Jacobians.

3.3 Vector Calculus :

Vector function, Introduction to double and triple integral, differentiation and integration of vector functions, gradient, divergence and curl, directional derivatives. Line, surface and volume integrals : Green, Gauss and Stokes's theorem, Green's theorem in plane.

4. INTEGRAL CALCULUS - II

4.1 Beta and Gamma Functions :

Definition, Use, Relation between the two, their use in evaluating integrals.

4.2 Fourier Series :

Fourier series of $f(x)$, $-n < x < n$, Odd and even function, Half range series.

4.3 Laplace Transform :

Definition, Basic theorem and properties, Unit step and Periodic functions, inverse laplace transform, Solution of ordinary differential equations.

5. PROBABILITY AND STATISTICS :

5.1 Probability :

Laws and Conditional probability

5.2 Distribution :

Discrete and continuous distribution.

5.3 Binomial Distribution :

Properties and application through problems.

5.4 Poisson Distribution :

Properties and application through problems

5.5 Normal Distribution :

Properties and applications through problems

5.6 Method of Least-squares.